

LECTURE NO 5

- 
- Conversion of a point into various coordinate systems

NUMERICALS

Given point $P(-2, 6, 3)$ and vector $\mathbf{A} = y\mathbf{a}_x + (x + z)\mathbf{a}_y$, express P and \mathbf{A} in cylindrical and spherical coordinates. Evaluate \mathbf{A} at P in the Cartesian, cylindrical, and spherical systems.

At point P : $x = -2, y = 6, z = 3$. Hence,

$$\rho = \sqrt{x^2 + y^2} = \sqrt{4 + 36} = 6.32$$

$$\phi = \tan^{-1} \frac{y}{x} = \tan^{-1} \frac{6}{-2} = 108.43^\circ$$

$$z = 3$$

$$r = \sqrt{x^2 + y^2 + z^2} = \sqrt{4 + 36 + 9} = 7$$

$$\theta = \tan^{-1} \frac{\sqrt{x^2 + y^2}}{z} = \tan^{-1} \frac{\sqrt{40}}{3} = 64.62^\circ$$

Thus,

$$P(-2, 6, 3) = P(6.32, 108.43^\circ, 3) = P(7, 64.62^\circ, 108.43^\circ)$$

For vector \mathbf{A} , $A_x = y$, $A_y = x + z$, $A_z = 0$. Hence, in the cylindrical system

$$\begin{bmatrix} A_\rho \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y \\ x + z \\ 0 \end{bmatrix}$$

or

$$A_\rho = y \cos \phi + (x + z) \sin \phi$$

$$A_\phi = -y \sin \phi + (x + z) \cos \phi$$

$$A_z = 0$$

But $x = \rho \cos \phi$, $y = \rho \sin \phi$, and substituting these yields

$$\begin{aligned} \mathbf{A} = (A_\rho, A_\phi, A_z) &= [\rho \cos \phi \sin \phi + (\rho \cos \phi + z) \sin \phi] \mathbf{a}_\rho \\ &+ [-\rho \sin^2 \phi + (\rho \cos \phi + z) \cos \phi] \mathbf{a}_\phi \end{aligned}$$

At P

$$\rho = \sqrt{40}, \quad \tan \phi = \frac{6}{-2}$$

Hence,

$$\cos \phi = \frac{-2}{\sqrt{40}}, \quad \sin \phi = \frac{6}{\sqrt{40}}$$

$$\begin{aligned} \mathbf{A} &= \left[\sqrt{40} \cdot \frac{-2}{\sqrt{40}} \cdot \frac{6}{\sqrt{40}} + \left(\sqrt{40} \cdot \frac{-2}{\sqrt{40}} + 3 \right) \cdot \frac{6}{\sqrt{40}} \right] \mathbf{a}_\rho \\ &\quad + \left[-\sqrt{40} \cdot \frac{36}{40} + \left(\sqrt{40} \cdot \frac{-2}{\sqrt{40}} + 3 \right) \cdot \frac{-2}{\sqrt{40}} \right] \mathbf{a}_\phi \\ &= \frac{-6}{\sqrt{40}} \mathbf{a}_\rho - \frac{38}{\sqrt{40}} \mathbf{a}_\phi = -0.9487 \mathbf{a}_\rho - 6.008 \mathbf{a}_\phi \end{aligned}$$

Similarly, in the spherical system

$$\begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \cos \theta \cos \phi & \cos \theta \sin \phi & -\sin \theta \\ -\sin \phi & \cos \phi & 0 \end{bmatrix} \begin{bmatrix} y \\ x + z \\ 0 \end{bmatrix}$$

But $x = r \sin \theta \cos \phi$, $y = r \sin \theta \sin \phi$, and $z = r \cos \theta$. Substituting these yields

$$\begin{aligned}\mathbf{A} &= (A_r, A_\theta, A_\phi) \\ &= r[\sin^2 \theta \cos \phi \sin \phi + (\sin \theta \cos \phi + \cos \theta) \sin \theta \sin \phi] \mathbf{a}_r \\ &\quad + r[\sin \theta \cos \theta \sin \phi \cos \phi + (\sin \theta \cos \phi + \cos \theta) \cos \theta \sin \phi] \mathbf{a}_\theta \\ &\quad + r[-\sin \theta \sin^2 \phi + (\sin \theta \cos \phi + \cos \theta) \cos \phi] \mathbf{a}_\phi\end{aligned}$$

At P

$$r = 7, \quad \tan \phi = \frac{6}{-2}, \quad \tan \theta = \frac{\sqrt{40}}{3}$$

Hence,

$$\begin{aligned}\cos \phi &= \frac{-2}{\sqrt{40}}, \quad \sin \phi = \frac{6}{\sqrt{40}}, \quad \cos \theta = \frac{3}{7}, \quad \sin \theta = \frac{\sqrt{40}}{7} \\ \mathbf{A} &= 7 \cdot \left[\frac{40}{49} \cdot \frac{-2}{\sqrt{40}} \cdot \frac{6}{\sqrt{40}} + \left(\frac{\sqrt{40}}{7} \cdot \frac{-2}{\sqrt{40}} + \frac{3}{7} \right) \cdot \frac{\sqrt{40}}{7} \cdot \frac{6}{\sqrt{40}} \right] \mathbf{a}_r \\ &\quad + 7 \cdot \left[\frac{\sqrt{40}}{7} \cdot \frac{3}{7} \cdot \frac{6}{\sqrt{40}} \cdot \frac{-2}{\sqrt{40}} + \left(\frac{\sqrt{40}}{7} \cdot \frac{-2}{\sqrt{40}} + \frac{3}{7} \right) \cdot \frac{3}{7} \cdot \frac{6}{\sqrt{40}} \right] \mathbf{a}_\theta \\ &\quad + 7 \cdot \left[\frac{-\sqrt{40}}{7} \cdot \frac{36}{40} + \left(\frac{\sqrt{40}}{7} \cdot \frac{-2}{\sqrt{40}} + \frac{3}{7} \right) \cdot \frac{-2}{\sqrt{40}} \right] \mathbf{a}_\phi \\ &= \frac{-6}{7} \mathbf{a}_r - \frac{18}{7\sqrt{40}} \mathbf{a}_\theta - \frac{38}{\sqrt{40}} \mathbf{a}_\phi \\ &= -0.8571 \mathbf{a}_r - 0.4066 \mathbf{a}_\theta - 6.008 \mathbf{a}_\phi\end{aligned}$$